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# GENERALISED RETARDED INTEGRAL INEQUALITIES IN ONE VARIABLE

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# **ABSTRACT**

In this paper, we obtain some linear as well as nonlinear retarded integral inequalities which can be used also tools in certain applications.

**KEYWORDS:** Retarded Integral Inequalities, Explicit Bound, Boundedness

### 1. INTRODUCTION

Integral inequalities play an important role in the qualitative analysis of differential and integral equations. Many retarded inequalities have been discovered [1-12]. Very recently Rashid in [12], obtained some new integral inequalities in one variables. In this paper we establish some new retarded integral inequalities, which generalize the main results of [12] which can be used as tools in the theory of differential equation with time delays which provide explicit bounds on unknown functions.

### 2. MAIN RESULTS

In what follows, R denotes the set of real numbers,  $R_+ = [0, \infty)$ ,  $R_+^* = (0, \infty)$ , J = [a, b] are given subsets of R. Let  $\Delta = J \times J$ . C  $(J, R_+)$  denotes the set of all continuous functions from J into  $R_+$  and  $C^1$  (J, J) denotes the set of all continuous differentiable function from J into J.

**Theorem 1:** Let  $u \in C$   $(J, R_+)$ , g, h,  $\delta_t$  g,  $\delta_t$  h  $C \in (\Delta, R_+)$  and  $f \in C$   $(J, R_+)$ ,  $\alpha \in C^1$  (J, J) be non-decreasing with  $\alpha$   $(t) \le t$  on J. If the inequality

$$u(t) \le f(t) + \int_{a}^{t} g(t, s) u(s) ds + \int_{a}^{\alpha(t)} h(t, s) u(s) ds$$
 (2.1)

holds, then

$$u(t) \le f(t) + \exp[G(t) + H(t)]$$
 (2.2)

where

G (t) = 
$$\int_{a}^{t} g(t, s) ds$$
 (2.3)

$$H(t) = \int_{a}^{\alpha(t)} h(t, s) ds$$
 (2.4)

**Proof:** Since f (t) is positive and non-decreasing (2.1) can rewrite as

$$\frac{\mathbf{u}(t)}{\mathbf{f}(t)} \le 1 + \int_{a}^{t} g(t,s) \, \mathbf{f}(s) \, \mathrm{d}s + \int_{a}^{\alpha(t)} h(t,s) \, \mathbf{f}(s) \, \mathrm{d}s$$

Let 
$$r(t) = \frac{u(t)}{f(t)}$$
 then

$$r(t) \le 1 + \int_{a}^{t} g(t,s) r(s) ds + \int_{a}^{\alpha(t)} h(t,s) r(s) ds$$
 (2.5)

Define a function z (t) by the right-hand side of (2.5) then we have

$$z(t) = 1 + \int_{a}^{t} g(t,s) r(s) ds + \int_{a}^{\alpha(t)} h(t,s) r(s) ds$$
 (2.6)

and 
$$r(t) < z(t)$$
,  $z(a) = 1$  (2.7)

Differentiating (2.6) with respect to t, we get

$$z'(t) = g(t,t) r(t) + \int_{a}^{(t)} \partial_{t} g(t,s) r(s) ds + h(t, \alpha(t)) r(\alpha(t) \alpha'(t) + \int_{a}^{\alpha(t)} \partial_{t} h(t,s) r(s) ds$$

$$(2.8)$$

using (2.7) we have,

$$z'(t) \le g(t,t) \ z(t) + \int_{a}^{t} \partial_{t} \ g(t,s) \ z(s) \ ds + h(t,\alpha(t)) \ z(\alpha(t) \ \alpha'(t) + \int_{a}^{\alpha(t)} \partial_{t} \ h(t,s) \ r(s) \ ds$$

$$z'(t) \le z(t) \{g(t,t) + \int_{a}^{t} \partial_{t} g(t,s) ds + h(t, \alpha(t)) \alpha'(t) + \int_{a}^{\alpha(t)} \partial_{t} h(t,s) ds \}$$

$$\frac{z'(t)}{z(t)} \le \frac{d}{dt} \left( \int_{a}^{t} g(t,s) \, ds \right) + \frac{d}{dt} \left( \int_{a}^{\alpha(t)} h(t,s) \, ds \right)$$

Integrating above inequality from a to t, we get

$$z(t) \le \exp \left[ \int_{a}^{t} g(t,s) ds + \int_{a}^{t} h(t,s) ds \right]$$

So

$$z(t) \le \exp[G(t) + H(t)]$$

where G (t) and H (t) are defined by (2.3) and (2.4)

As 
$$r(t) \le z(t)$$
, we get

$$r(t) \le \exp[G(t) + H(t)]$$

Hence

(2.9)

$$u(t) \le f(t) \exp [G(t) + H(t)].$$

**Theorem 2:** Let  $u \in C$   $(J, R_+)$ ,  $g, h, \delta_t g, \delta_t h \in C$   $(\Delta, R_+)$  and  $F \in C$   $(J, R_+)$ ,  $\alpha \in C^1$  (J, J) be non-decreasing with  $\alpha$   $(t) \le t$  on J and p > 1 is a constant. If the inequality

$$u^{P}(t) \le f^{P}(t) + \int_{a}^{t} g(t,s) u(s) ds + \int_{a}^{\alpha(t)} h(t,s) u(s) ds$$
 (2.10)

holds, then

$$u(t) \le f(t) \left[ 1 + \left( \frac{p-1}{p} \right) [Q(t) + W(t)] \right]^{\frac{1}{p-1}}$$
 (2.11)

where

$$Q(t) = \int_{a}^{t} f^{1-P}(s) g(t, s) ds$$
 (2.12)

and

$$W(t) = \int_{a}^{\alpha(t)} f^{1-P}(s) h(t, s) ds$$
 (2.13)

**Proof:** Since f (t) is positive and non-decreasing we can rewrite (2.10) as

$$\frac{u^{p}(t)}{f^{p}(t)} \le 1 + \int_{a}^{t} g(t,s) f^{1-p}(s) \frac{u(s)}{f(s)} ds + \int_{a}^{\alpha(t)} (t,s) f^{1-p}(s) \frac{u(s)}{f(s)} ds$$
(2.14)

Let 
$$r(t) = \frac{u(t)}{f(t)}$$
, then

$$r^{P}(t) \le 1 + \int_{a}^{t} g(t,s) f^{1-P}(s) r(s) ds + \int_{a}^{\alpha(t)} (t,s) f^{1-P}(s) r(s) ds$$
 (2.15)

Define a function z (t) by the right-hand side of (2.15) then we have

$$z(t) = 1 + \int_{a}^{t} g(t,s) f^{1-P}(s) r(s) ds + \int_{a}^{\alpha(t)} h(t,s) f^{1-P}(s) r(s) ds$$

$$r^{P}(t) \le z(t), z(a) = 1$$
 (2.17)

Differentiating (2.16) with respect to t, we get

$$z^{'}(t) = g(t,t) f^{1-P}(t) r(t) + \int_{a}^{t} \partial_{t} g(t,s) f^{1-P}(s) r(s) ds + h(\alpha(t),t) f^{1-P}(\alpha(t)) r(\alpha(t))$$

$$\alpha'(t) + \int_{a}^{\alpha(t)} \partial_{t} h(t,s,) f^{1-P}(s) r(s) ds$$
 (2.18)

Using (2.17) in (2.18), we get,

$$z^{'}(t) \leq g(t,t) f^{1-P}(t) z^{\frac{1}{P}}(t) + \int_{a}^{t} \partial_{t} g(t,s) f^{1-P}(s) z^{\frac{1}{P}}(s) + h(t,\alpha(t)) f^{1-P}(\alpha(t)) z^{\frac{1}{P}}(\alpha(t)) \alpha^{'}(t) + \int_{a}^{\alpha(t)} \partial_{t} h(t,s) f^{1-P}(s)$$

 $z^{\frac{1}{P}}$  (s) ds

Hence.

$$z'(t). \ z^{-\frac{1}{P}}(t) \le g(t,t) \ f^{1-P}(t) + \int_{a}^{t} \partial_{t} \ g(t,s) \ f^{1-P}(s) \ ds + h(t,\alpha(t)) \ f^{1-P}(\alpha(t)) \ \alpha'(t) + \int_{a}^{\alpha(t)} \partial_{t} \ h(t,s) \ f^{1-P}(s) \ ds$$
 (2.19)

or

$$\frac{dz(t)}{z^{\frac{1}{P}}(t)} \le \frac{d}{dt} \left( \int_{a}^{t} g(t,s) f^{1-P}(s) ds \right) + \frac{d}{dt} \left( \int_{a}^{\alpha(t)} h(t,s) f^{1-P}(s) ds \right)$$
(2.20)

Integrating from a to t and making change of variable, we have

$$\frac{P}{P-1} z^{\frac{P-1}{1}} - \frac{P}{P-1} \le \int_{a}^{t} g(t,s) f^{1-P}(s) ds + \int_{a}^{\alpha(t)} h(t,s) f^{1-P}(s) ds + c$$
 (2.21)

Using z (a) = 1, we have  $c \ge 0$ , Hence

$$z\left(t\right) \leq \left[1 + \left(\frac{P-1}{P}\right) \!\!\left[\int\limits_{a}^{t} g(t,s) f^{1-P}(s) ds + \int\limits_{a}^{t} h(t,s) f^{1-P}(s) ds\right]\right]^{\frac{P}{P-1}}$$

OR

$$z(t) \le \left[1 + \left(\frac{P-1}{P}\right) [Q(t) + W(t)]\right]^{\frac{P}{P-1}}$$
 (2.22)

Where Q(t) and W(t) are defined by (2.12) and (2.13).

Using (2.17) in (2.22) we get,

$$r(t) \leq \left[1 + \left(\frac{P-1}{P}\right) \left[Q(t) + W(t)\right]\right]^{\frac{1}{P-1}}$$

so

$$u(t) \le f(t) \left[ 1 + \left( \frac{P-1}{P} \right) \left[ Q(t) + W(t) \right] \right]^{\frac{1}{P-1}}.$$

**Theorem 2.3:** Let  $u \in C$   $(J, R_+)$ , g, h,  $\delta_t$  g,  $\delta_t$   $h \in C$   $(\Delta, R_+)$  and  $f \in C$   $(J, R_+)$ ,  $\alpha \in C^1$  (J, J) be non-decreasing with  $\alpha$   $(t) \le t$  on J. For i = 1, 2, let  $\psi_i C$   $(R_+, R_+)$  be non-decreasing function with  $\psi_i$  (u) > 0 for u > 0 and  $\frac{\psi_i u(t)}{f(t)} < \psi_i \left(\frac{u(t)}{f(t)}\right)$ .

If the inequality

$$u(t) \le f(t) + \int_{a}^{t} g(t,s) \psi_{1}(u(s)) ds + \int_{a}^{t} h(t,s) \psi_{2}(u(s)) ds$$
 (2.23)

Then for  $a \le t \le t$ ,

i) in case  $\psi_1(u) \le \psi_1(u)$   $u(t) \le f(t) \phi_2^{-1} [\phi_2(1) + G(t) + H(t)]$  (2.24)

ii) in case 
$$\psi_2(u) \le \psi_1(u)$$
 
$$u(t) \le f(t) \phi_1^{-1} [\phi_1(1) + G(t) + H(t)]$$
 (2.25)

where G (t) and H (t) are defined by (2.3) and (2.4) and for  $i = 1, 2 \varphi_t^{-1}$  are the inverse functions of

$$\phi_i(r) = \int_{r_0}^{r} \frac{ds}{\psi_i(s)}, r > 0, r_0 > 0$$

and  $t_{1} \in J$  is chosen so that  $\phi_{1}\left(1\right) + G\left(t\right) + H\left(t\right) \in Dom\left(\phi_{i}^{-1}\right)$ , respectively, for all t in  $[a,t_{1}]$ 

**Proof:** Since f (t) is positive and non-decreasing we can restate (2.23) as

$$\frac{u(t)}{f(t)} \le 1 + \int_{a}^{t} g(t,s) \frac{\psi_{1}(u(s))}{f(s)} ds + \int_{a}^{\alpha(t)} h(t,s) \frac{\psi_{2}(u(s))}{f(s)} ds$$

$$\leq 1 + \int_{a}^{t} g(t,s) \psi_{1}\left(\frac{u(s)}{f(s)}\right) ds + \int_{0}^{\alpha(t)} h(t,s) \psi_{2}\left(\frac{u(s)}{f(s)}\right) ds$$

Let  $r(t) = \frac{u(t)}{f(t)}$ . Hence, we have

$$r(t) \le 1 + \int_{a}^{t} g(t,s) \psi_{1}(r(s)) ds + \int_{a}^{\alpha(t)} h(t,s) \psi_{2}(r(s)) ds$$
 (2.26)

Define z (t) by the right-hand side of (2.26), we have

$$z(t) = 1 + \int_{a}^{t} g(t,s) \psi_{1}(r(s)) ds + \int_{a}^{\alpha(t)} h(t,s) \psi_{2}(r(s)) ds$$
 (2.27)

Then it is clear that

$$r(t) \le z(t), z(a) = 1$$
 (2.28)

Now,

$$z'(t) = g(t,t) \psi_1(r(t)) + \int_a^t \partial_t g(t,s) \psi_1(r(s)) ds + h(t,\alpha(t)) \alpha'(t)$$

+ 
$$\int_{a}^{\alpha(t)} \partial_{t} h(t,s) \psi_{2}(r(s)) ds$$

$$\leq g(t,t) \psi_{1}(z(t)) + \int_{a}^{t} \partial_{t} g(t,s) \psi_{1}(z(s)) ds + h(t,\alpha(t)) \psi_{2}(z(t)) \alpha'(t)$$

+ 
$$\int_{a}^{\alpha(t)} \partial_{t} h(t,s) \psi_{2}(z(s)) ds$$

In case  $\psi_1(\mathbf{r}(t)) \leq \psi_2(\mathbf{r}(t))$ , we have

$$z'(t) \leq \psi_2(z(t)) \left[ g(t,t) + \int_a^t \partial_t g(t,s) ds + h(t,\alpha,(t)) \alpha'(t) + \int_a^t \partial_t h(t,s) ds \right]$$

$$z'(t) \le \psi_2(z(t)) \left[ \frac{d}{dt} \left( \int_a^t g(t,s) ds \right) + \frac{d}{dt} \left( \int_a^{\alpha(t)} h(t,s) ds \right) \right]$$

there fore

$$\frac{d}{dt}\phi_2(z(t)) = \frac{z^1(t)}{\psi_2(z(t))} = \frac{d}{dt} \left( \int_a^t g(t,s)ds \right) + \frac{d}{dt} \left( \int_a^{\alpha(t)} h(t,s)ds \right)$$
(2.29)

Integrating (2.29) from a to t and using condition z (a) = 1, we get

$$\phi_2(z(t)) = \int_a^t g(t,s) ds + \int_a^{\alpha(t)} h(t,s) ds + \phi_2(1)$$
(2.30)

Hence

$$z(t) = \phi_2^{-1} \left[ \int_a^t g(t,s) ds + \int_a^{\alpha(t)} h(t,s) ds + \phi_2(1) \right]$$
 (2.31)

i.e. 
$$z(t) = \phi_2^{-1} [G(t) + H(t) + \phi_2(1)]$$
 (2.32)

Using (2.28) in (2.32), we get the desired result. Since the proof of case (ii) is similar to case (i) we omit the details.

# 3. APPLICATIONS

In this section we present application of the inequality in Theorem 1 to study the boundedness of the solutions of the retarded differential equations.

First we consider the functional differential equation

$$x'(t) = F(s,t, x(t), x(t-h(t)))$$
 (3.1)

with initial condition

$$x(c) = x_0, x \ge 0 (3.2)$$

where  $F \in C(J \times J \times R^2, R)$ ,  $h \in C^1(J, R_+)$  such that  $t - h(t) \ge 0$ , h'(t) < 1 and h(0) = 0.

The following theorem deals with a bound on the solution of the problem (3.1).

**Theorem 3.1:** Assume that  $F: J \times J \times R^2 \to R$  is a continuous function. There exists continuous function g(s,t), h(s,t) for s, t,  $\in J$  such that

$$|F(s,t,u,v)| \le g(s,t) |u| + h(s,t) |v| \tag{3.3}$$

and 
$$|x_0| \le k$$
 where  $k > 0$  is a constant and let  $M = \frac{max}{t \in J} \frac{1}{1 - h'(t)}$  (3.4)

If x (t) is any solution of (3.1) then

$$|\mathbf{x}(t)| < |\mathbf{x}_0| \exp \left( \int_{a}^{t} g(s,t)dt + \int_{a}^{\alpha(t)} \overline{h}(s,\tau)d\tau \right)$$

**Proof:** The solution x(t) of the problem (3.1) can be written as

$$x(t) = x_0 + \int_a^t F(s, \sigma, x(\sigma), x(\sigma - h(\sigma))) d\sigma$$
(3.4)

using (3.2), (3.3), (3.4) and making change of variables, we have

$$|x(t)| \le |x_0| + \int_a^t g(s, \sigma) |x(\sigma)| d\sigma + \int_a^t h(s, \sigma) (x(\sigma - h(\sigma))) d\sigma$$

$$(3.5)$$

$$\leq |x_0| + \int_a^t g(s, \sigma) |x(\sigma)| d\sigma + \int_a^{t-h(t)} \frac{1}{h}(\tau) |x(\tau)| d\tau \tag{3.6}$$

for  $t \in J$  where  $\overline{h}(\tau) = M h(\tau + h(\sigma), \sigma, \tau \in J$ .

Now a suitable application of the inequality in Theorem 2.1 to (3.6) yields the results.

# CONCLUSIONS

The above inequalities can be extended to two variable case, which can further generalized to study qualitative properties of partial differential equations.

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